

# Kvaser PCIEcan 4xHS User's Guide



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<http://www.kvaser.com>

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We believe that the information contained herein was accurate in all respects at the time of printing. Kvaser AB cannot, however, assume any responsibility for errors or omissions in this text. Also note that the information in this document is subject to change without notice and should not be construed as a commitment by Kvaser AB.

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## **1 About this manual**

This manual is intended for Kvaser PCIEcan 4xHS users. This document contains a description of the hardware's properties and general instructions for connecting the device to a computer.

## 2 Introduction

This section will describe the functions and features of the Kvaser PCIEcan 4xHS.

### 2.1 Welcome to Kvaser PCIEcan 4xHS

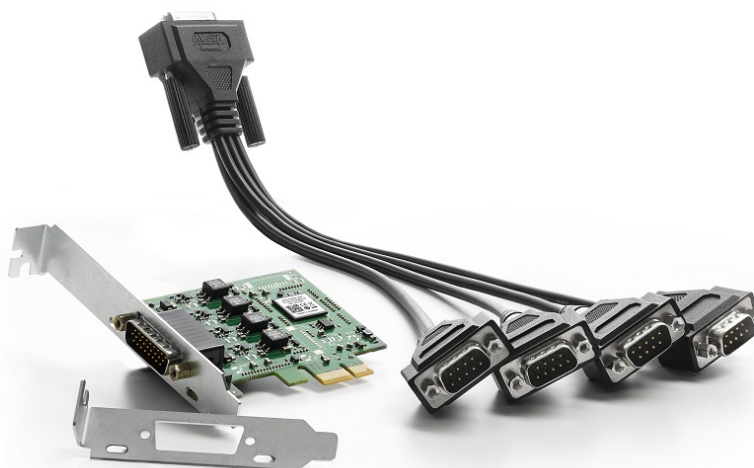


Figure 1: Kvaser PCIEcan 4xHS

Kvaser PCIEcan 4xHS is a small, yet advanced, CAN multi channel real time CAN interface that handles transmission and reception of standard and extended CAN messages on the bus with a high time stamp precision. It is compatible with applications that use Kvaser's CANlib.

This guide applies to Kvaser PCIEcan 4xHS devices listed in Table 1.

| Device              | Product Number (EAN) |
|---------------------|----------------------|
| Kvaser PCIEcan 4xHS | 73-30130-00683-6     |

Table 1: Kvaser PCIEcan 4xHS devices and their product numbers.

## 2.2 Major features

- PCI Express CAN interface.
- Supports CAN FD, up to 8 Mbit/s (with proper physical layer).
- Quick and easy plug-and-play installation.
- Supports both 11-bit (CAN 2.0A) and 29-bit (CAN 2.0B active) identifiers.
- 100 % compatible with applications written for other Kvaser CAN hardware with Kvaser CANlib.
- High-speed CAN connection (compliant with ISO 11898-2), up to 1 Mbit /s.
- Fully compatible with J1939, CANopen, NMEA 2000 and DeviceNet.
- Supports silent mode for analysis tools – listen to the bus without interfering.
- Simultaneous operation of multiple devices.
- Low profile board.
- Includes 4 channel breakout cable.

## 2.3 Interface

Kvaser PCIEcan 4xHS provides a CAN bus interface through a standard PCI Express x1 interface.

## 2.4 Additional software and documentation

The Kvaser CANlib SDK includes everything you need in order to develop software applications interacting with Kvaser CAN hardware. The SDK contains full documentation and many sample programs, written in C, C++, C#, Delphi, Python and Visual Basic. Kvaser CAN hardware is built around the same common software API. Applications developed using one device type will run without modification on other device types.

The latest versions of documentation, software and drivers can be downloaded for free at [www.kvaser.com/download](http://www.kvaser.com/download).

## 3 Kvaser PCIEcan 4xHS hardware

In this section you can read more about the CAN channels, power supply and LED indicators.

### 3.1 Hardware installation

The Kvaser PCIEcan 4xHS may be inserted in any free PCI Express slot on the host computer. You do need to switch the power off before inserting or removing the device.

### 3.2 CAN channels

The Kvaser PCIEcan 4xHS has four CAN Hi-Speed channels in a single 26-pin HD D-SUB CAN connector (see Figure 2). See Section 4.2, CAN connectors, on Page 9 for pinout information.



Figure 2: CAN connector on Kvaser PCIEcan 4xHS

### 3.3 Power supply

The Kvaser PCIEcan 4xHS is powered from the PCI Express connector.

### 3.4 LED Indicators

The Kvaser PCIEcan 4xHS has four yellow LED indicators, one for each channel, that indicates with a short flash that a CAN message was received or sent. A single flash may be hard to see and a continuous set of flashes will be indistinguishable from a steady light.

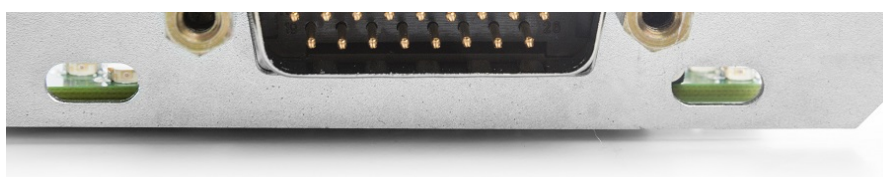


Figure 3: LEDs on the Kvaser PCIEcan 4xHS.

### 3.5 Troubleshooting

Use “Kvaser Device Guide” in the Control Panel to verify that the computer can communicate with the Kvaser PCIEcan 4xHS. If the firmware version shown is all zeros, there are communication problems.



## 4 Appendices

In this section you will find technical information about the Kvaser PCIEcan 4xHS and its connectors.

### 4.1 Technical data

In Table 2 below you will find the Kvaser PCIEcan 4xHS's technical specifications.

|                        |  |
|------------------------|--|
| CAN Channels           | 4  |
| CAN Transceivers       | MCP2561FD (Compliant with ISO 11898-2)   |
| CAN Controller         | Kvaser CAN IP in FPGA  |
| Galvanic isolation     | Yes  |
| CAN Bit Rate           | 40 kbit/s to 1 Mbit/s "Classic CAN"  |
| CAN FD Bit Rate        | Up to 8 Mbit/s (with correct physical layer implementation)  |
| Time stamp resolution  | 1 $\mu$ s  |
| Max message rate       | 20000 msg/s per channel  |
| Error Frame Detection  | Yes  |
| Error Frame Generation | Yes  |
| Silent mode            | Yes  |
| Power consumption      | Typically 700 mW idle plus max 150 mW per channel, i.e. max 1300 mW for a four channel interface. Only uses 3.3 V. |
| PC interface           | PCI Express  |
| Hardware configuration | Done by software.  |
| Software requirements  | Windows Vista or later. (For other operating systems, contact Kvaser support.)                                     |
| Dimensions             | Low profile, 86 x 69 mm  |
| Weight                 | 50 g (200g including HD26-4DS9 Splitter)   |
| Operating temperature  | 0 °C to +85 °C   |
| Storage temperature    | -40 °C to +85 °C   |
| Relative humidity      | 0 % to 85 % (non-condensing.)  |

Table 2: Technical Specifications.

### 4.2 CAN connectors

Kvaser PCIEcan 4xHS devices that use the 26-pin HD D-SUB connector (see Figure 4 on Page 10) have the pinning described in Table 3 on Page 10. This table also describes how the HD26-4xDS9 splitter (see Figure 6 on Page 11) connects to four separate 9-pin D-SUB connectors, CAN 1 to CAN 4.

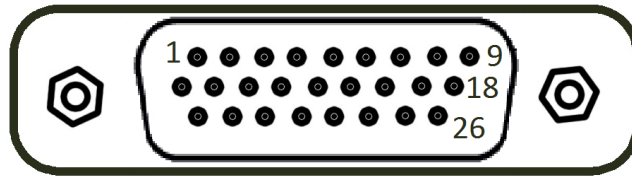


Figure 4: The male 26 pin HD D-SUB connector pin numbers

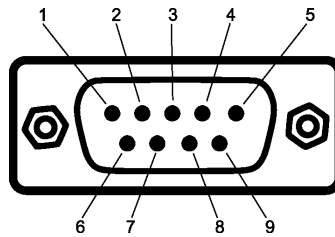


Figure 5: The male D-SUB 9 connector pin numbers

| HD D-SUB | CAN 1 | CAN 2 | CAN 3 | CAN 4 | Function                        |
|----------|-------|-------|-------|-------|---------------------------------|
| 1        | 2     |       |       |       | CAN_L channel 1                 |
| 2        |       | 2     |       |       | CAN_L channel 2                 |
| 3        |       |       | 2     |       | CAN_L channel 3                 |
| 4        |       |       |       | 2     | CAN_L channel 4                 |
| 5        |       |       |       |       | Not connected                   |
| 6        |       |       |       |       | Not connected                   |
| 7        |       |       |       |       | Not connected                   |
| 8        | 4     |       |       |       | Not used by Kvaser PCIEcan 4xHS |
| 9        |       |       |       |       | Not connected                   |
| 10       | 9     |       |       |       | Not used                        |
| 11       | 7     |       |       |       | CAN_H channel 1                 |
| 12       |       | 7     |       |       | CAN_H channel 2                 |
| 13       |       |       | 7     |       | CAN_H channel 3                 |
| 14       |       |       |       | 7     | CAN_H channel 4                 |
| 15       |       |       |       |       | Not connected                   |
| 16       |       |       |       |       | Not connected                   |
| 17       |       |       |       |       | Not connected                   |
| 18       |       | 4     |       |       | Not used by Kvaser PCIEcan 4xHS |
| 19       | 3     |       |       |       | GND channel 1                   |
| 20       |       | 3     |       |       | GND channel 2                   |
| 21       |       |       | 3     |       | GND channel 3                   |
| 22       |       |       |       | 3     | GND channel 4                   |
| 23       |       |       |       |       | Not connected                   |
| 24       |       |       |       |       | Not connected                   |
| 25       |       |       |       |       | Not connected                   |
| 26       |       |       |       |       | Not connected                   |

Table 3: Pin configuration of the 26-pin HD D-SUB (and HD26-4xDS9 splitter)



Figure 6: The HD26-4xDS9 Splitter

### 4.3 CAN bus termination

Every CAN bus must be terminated with a 120 Ohm resistor at each end of the bus. The Kvaser PCIEcan 4xHS does not contain any CAN bus termination, because their inclusion could cause severe disturbance in a system which is already correctly terminated.

For laboratory or testing use, the exact value of the termination resistors is not always critical. Sometimes a single terminator is sufficient. For production, proper termination is essential. If you see error frames on the bus, you should check the termination.



**To save yourself a lot of trouble, always terminate the CAN bus properly.**

### 4.4 Updating the firmware

For the Kvaser PCIEcan 4xHS to communicate with the host computer, compatible versions of the Kvaser CANlib (including driver) and firmware must be installed.

The latest versions of firmware and drivers can be downloaded for free at [www.kvaser.com/download](http://www.kvaser.com/download).

Connect the Kvaser PCIEcan 4xHS to your PC with the USB cable and start the update.exe application. A window opens showing the Firmware Update Instructions, read and follow those carefully.

To check the current firmware version, open "Kvaser Device Guide" which can be found in the Control Panel. Select "Kvaser PCIEcan 4xHS" in the tree view to the left, and click on the channel. The firmware revision information now appears in the right half of the window.

## 5 Disposal and Recycling Information



When this product reaches its end of life, please dispose of it according to your local environmental laws and guidelines.

For information about Kvaser's recycling programs, visit:  
<http://www.kvaser.com/en/kvaser/recycling-policy.html>

## 6 Legal acknowledgements

### 6.1 Usage warning



#### **WARNING FOR ALL USERS**

WARNING! - YOUR USE OF THIS DEVICE MUST BE DONE WITH CAUTION AND A FULL UNDERSTANDING OF THE RISKS!

THIS WARNING IS PRESENTED TO INFORM YOU THAT THE OPERATION OF THIS DEVICE MAY BE DANGEROUS. YOUR ACTIONS CAN INFLUENCE THE BEHAVIOR OF A CAN-BASED DISTRIBUTED EMBEDDED SYSTEM, AND DEPENDING ON THE APPLICATION, THE CONSEQUENCES OF YOUR IMPROPER ACTIONS COULD CAUSE SERIOUS OPERATIONAL MALFUNCTION, LOSS OF INFORMATION, DAMAGE TO EQUIPMENT, AND PHYSICAL INJURY TO YOURSELF AND OTHERS. A POTENTIALLY HAZARDOUS OPERATING CONDITION IS PRESENT WHEN THE FOLLOWING TWO CONDITIONS ARE CONCURRENTLY TRUE: THE PRODUCT IS PHYSICALLY INTERCONNECTED TO A REAL DISTRIBUTED EMBEDDED SYSTEM; AND THE FUNCTIONS AND OPERATIONS OF THE REAL DISTRIBUTED EMBEDDED SYSTEM ARE CONTROLLABLE OR INFLUENCED BY THE USE OF THE CAN NETWORK. A POTENTIALLY HAZARDOUS OPERATING CONDITION MAY RESULT FROM THE ACTIVITY OR NON-ACTIVITY OF SOME DISTRIBUTED EMBEDDED SYSTEM FUNCTIONS AND OPERATIONS, WHICH MAY RESULT IN SERIOUS PHYSICAL HARM OR DEATH OR CAUSE DAMAGE TO EQUIPMENT, DEVICES, OR THE SURROUNDING ENVIRONMENT.

WITH THIS DEVICE, YOU MAY POTENTIALLY:

- CAUSE A CHANGE IN THE OPERATION OF THE SYSTEM, MODULE, DEVICE, CIRCUIT, OR OUTPUT.
- TURN ON OR ACTIVATE A MODULE, DEVICE, CIRCUIT, OUTPUT, OR FUNCTION.
- TURN OFF OR DEACTIVATE A MODULE, DEVICE, CIRCUIT, OUTPUT, OR FUNCTION.
- INHIBIT, TURN OFF, OR DEACTIVATE NORMAL OPERATION.
- MODIFY THE BEHAVIOR OF A DISTRIBUTED PRODUCT.
- ACTIVATE AN UNINTENDED OPERATION.
- PLACE THE SYSTEM, MODULE, DEVICE, CIRCUIT, OR OUTPUT INTO AN UNINTENDED MODE.

ONLY THOSE PERSONS WHO:

(A) ARE PROPERLY TRAINED AND QUALIFIED WITH RESPECT TO THE USE OF THE DEVICE,

(B) UNDERSTAND THE WARNINGS ABOVE, AND

(C) UNDERSTAND HOW THIS DEVICE INTERACTS WITH AND IMPACTS THE FUNCTION AND SAFETY OF OTHER PRODUCTS IN A DISTRIBUTED SYSTEM AND THE APPLICATION FOR WHICH THIS DEVICE WILL BE APPLIED, MAY USE THE DEVICE.

PLEASE NOTE THAT YOU CAN INTEGRATE THIS PRODUCT AS A SUBSYSTEM INTO HIGHER-LEVEL SYSTEMS. IN CASE YOU DO SO, KVASER AB HEREBY DECLARES THAT KVASER AB'S WARRANTY SHALL BE LIMITED TO THE CORRECTION OF DEFECTS, AND KVASER AB HEREBY EXPRESSLY DISCLAIMS ANY LIABILITY OVER AND ABOVE THE REFUNDING OF THE PRICE PAID FOR THIS DEVICE, SINCE KVASER AB DOES NOT HAVE ANY INFLUENCE ON THE IMPLEMENTATIONS OF THE HIGHER-LEVEL SYSTEM, WHICH MAY BE DEFECTIVE.

## 6.2 EU Regulatory Compliance



### EU Declaration of Conformity (DoC)

**We**

|                 |               |                   |                  |
|-----------------|---------------|-------------------|------------------|
| Company Name:   | Kvaser AB     | City:             | Mölndal          |
| Postal address: | Aminogatan 25 | Telephone number: | +46 31 886344    |
| Postcode:       | 431 53        | E-mail address:   | sales@kvaser.com |

**declare that the DoC is issued under our sole responsibility and belongs to the following product:**

Product: Kvaser PCIEcan 4xHS

**Object of the declaration** (identification of apparatus allowing traceability):

Product: Kvaser PCIEcan 4xHS

Type: 73-30130-00683-6

**The object of the declaration described above is in conformity with the relevant Union harmonisation legislation:**

Electromagnetic Compatibility (EMC) Directive 2014/30/EU (Art. 6)

RoHS recast Directive 2011/65/EU (Art. 4.1)

**The following harmonised standards and technical specifications have been applied**  
(title, date of standard/specification):

EN 55024 (2010)

EN 55032 (2012)

EN 61000-6-2 (2005)

EN 61000-6-3 (2007 + A1:2011)

EN 50581 (2012)


**Signed for and on behalf of:**

Mölndal

2018-10-04

Place of issue

Date of issue

  
Claes Haglund, Supply Chain and Quality director

**NOTE:** This equipment has been tested and found to comply with the limits for a Class A digital device, pursuant to Part 15 of the FCC Rules. These limits are designed to provide reasonable protection against harmful interference when the equipment is operated in a commercial environment. This equipment generates, uses, and can radiate radio frequency energy and, if not installed and used in accordance with the instruction manual, may cause harmful interference to radio communications. Operation of this equipment in a residential area is likely to cause harmful interference in which case the user will be required to correct the interference at his/her own expense.

### 6.3 Patents, Copyrights and Trademarks

All trademarks are the property of their respective owner. Windows is a registered trademark of Microsoft Corporation in the United States and other countries.

Adobe, the Adobe logo, and Reader are either registered trademarks or trademarks of Adobe Systems Incorporated in the United States and/or other countries.

MagiSync is a trademark of Kvaser AB.

DeviceNet is a trademark of Open DeviceNet Vendor Association, Inc.

NMEA 2000 is the registered trademark of the National Marine Electronics Association, Inc.

For information about Kvaser related CAN patents, see [www.kvaser.com/patent](http://www.kvaser.com/patent).



## 7 Document Revision History

Version history for document UG\_98168\_pciecan:

| Revision | Date       | Changes  |
|----------|------------|--|
| 1.0      | 2015-04-28 | Initial version                                      |
| 1.1      | 2015-08-11 | Minor textual changes                                |
| 1.2      | 2016-02-04 | Added chapter: Updating the firmware                 |
| 1.3      | 2017-01-09 | Updated compliance text, added link to patents       |
| 1.4      | 2017-03-21 | Added Power consumption to Technical data.           |
| 2.0      | 2017-08-25 | Updated EU Declaration of Conformity                 |
| 2.1      | 2018-01-29 | "Kvaser Device Guide" has replaced "Kvaser Hardware" |
| 2.2      | 2018-05-03 | Minor textual changes                                |
| 2.3      | 2018-08-28 | Minor textual changes                                |
| 3.0      | 2018-10-15 | Updated EU Regulatory Compliance                     |
| 3.1      | 2019-02-11 | Minor textual changes                                |